GEOS 28600

The science of landscapes: Earth & Planetary Surface Processes

Lecture 1 Monday 1 October 2018

Introduction. Shape, geoid, true polar wander.

INTRODUCTION

SHAPE (HYDROSTATIC, $\rho = \rho(r)$)

GEOID (WHAT IS TOPOGRAPHY MEASURED RELATIVE TO?)

TRUE POLAR WANDER

Logistics

Class website:

http://geosci.uchicago.edu/~kite/geos28600_2018/

6 problem sets, 5 labs

Grading scheme: 60% homework, 30% final, 10% class participation. Final will be closed-book, but you will be allowed to take in 1 sheet of letter-sized paper with notes.

We study landscapes to gain a process understanding and to understand planetary history



Earth's surface. Tectonics, aeolian processes, fluvial processes: $H_2O_1 \approx 300K$

Landscapes result from competition between geologic processes

 Know the processes, their rates, and the controls on those rates, and you have a scientific understanding of the landscape.

History: Fluid envelopes (atmosphere, ocean) permit life on Earth. Planets with solid surfaces retain traces of the evolution of their fluid envelopes over geological time.



Titan's surface. Fluvial processes: CH₄, ~80K



Apollo 15 Commander Dave Scott is picking up the Apollo Lunar Surface Drill at the ALSEP site. In the center is Mount Hadley and on the right, Lunar Module Falcon sits in front of the Swann Range

Moon's surface. relatively simple: impact cratering + hillslope processes. Fundamentals



Mars surface. Weathering, soil formation, aeolian processes intermediate complexity; history of fluvial processes

Ancient sediments on Mars



Sedimentary basins: time series of constraints on surface processes Sedimentology, basin analysis

Course progression



$\mathsf{FLYBY} \to \mathsf{ORBIT} \to \mathsf{LAND} \to \mathsf{ROVE}$

Pluto

Mercury

Titan

Mars, Earth

Lectures (plan: 2 per topic)



Labs

- Sand dune formation (computer)
- Mars Exploration Rover analyst's notebook (Eagle crater)
- Landscape evolution modeling (computer)
- Mars landing site selection

Key points from today's lecture

- why planets are roughly spherical; relationship between internal mass distribution and rotational bulge.
- the definition of the geoid;
- principle of true polar wander; evidence for true polar wander.

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Why do large worlds have round shapes?

in this course: worlds = (planets + dwarf planets + moons + large KBOs)



Pluto, dwarf planet 2400 km diameter; ice



Charon, moon 1200 km diameter; ice



Vesta, asteroid 525 km diameter; rock

$$P_c = \frac{3GM^2}{8\pi R^4}$$

pressure or temperature?

do materials matter?

does time matter?

Why do large worlds have round shapes?



stress difference at failure/2

$$P_c = \frac{3GM^2}{8\pi R^4}$$

(Max-Min)/Mean Radius

Why do large worlds have round shapes?

effect of temperature? Pla			nets are born hot and cool over time		
strain rate, s ⁻¹ $\dot{\mathcal{E}}_{steady} = A_c \sigma^{n}$	$e^{-g\frac{T_m}{T}}$	$e^{-g \frac{T_m}{T}}$ $e^{-g \frac$			eform ose to the that are not got close to were ooled.
	A _c		Q^*	T_m	g
Material	$(MPa^{-n} s)$	n	(kJ/mol)	(K)	$= Q/RT_m$
Olivine				2200	27
Dry	1.2×10^2	3.0	502		
Water ice, Ih, ^d T > 258 K $\sigma > 1$ MPa	6.3×10^{28}	4	181	273	80
Hydro	ostatic assumpt	tion: pres solid	sure is balanc d worlds beha	ed by grav ve like flu	vity iids
Strength also reduces on annroach		/			1
to melting point	sufficien	tly large		over geo at large	ologic time & spatial scales



Silly putty



Does time matter? (Maxwell time)

timescale over which solids behave like fluids?

$$\dot{\mathcal{E}}_{\text{total}} = \dot{\mathcal{E}}_{\text{elastic}} + \dot{\mathcal{E}}_{\text{viscous}}$$

$$\dot{\mathcal{E}}_{\text{total}} = \dot{\sigma}/2\mu + \sigma/2\eta$$

$$\stackrel{\text{elastic}}{\stackrel{\text{shear modulus}}{\stackrel{\text{shear modulus}}{\stackrel{\text{pa}}{=}}}$$

$$\tau_M \equiv \frac{\eta}{\mu} \quad \frac{P_{\text{pa}}}{P_{\text{pa}} \text{ s}^{-1}}$$

Material	Shear modulus, μ (GPa)	Viscosity, η (Pa–s)	Maxwell time, $\tau_{_{M}}$
Soda-lime glass @ 250°C	25	4.3×10^{11}	17 s
Glacier ice @ 0°C	4	~1013	42 min
Halite @ 200°C	20	3×10^{16}	17 days
Earth mantle from glacial rebound	50	1020	66 yr

as far as we know, all worlds in the solar system formed ~4.6 Gyr ago

Why do planets in hydrostatic equilibrium bulge at the equator?



 $m = \frac{\omega^2 a^3}{GM} \cong \frac{3}{4\pi} \frac{\omega^2}{G\overline{\rho}}$ f = (a-c)/a = f(m) = ?

Assume: m<<1; no fluid circulation. Basic criterion: no tangential forces at surface.

f 🗙 m

Hydrostatic equilibrium: pressure at the bottom of column-of-water (a) = pressure at the bottom of column-of -water (c)

"the appropriate theory [for the proportionality constant relating *f* and *m*] is quite nasty ... and rather little insight emerges from wallowing in the nastiness."

How much do planets in hydrostatic equilibrium bulge at the equator?



Hydrostatic equilibrium as $m \rightarrow 1$



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Reference ellipsoid, vs. geoid, vs. topography



distance along a line of longitude

Gravity of fluid planet = hydrostatic equilibrium + fluid circulation





Kaspi et al. GRL 2010 Hubbard Icarus 1999



Figure 3.9. Schematic figure showing possible correlation between Jupiter "topography" produced by cylindrical zonal flows and gravity anomalies (arrows). The vectors to the right represent gravity anomalies calculated with respect to a planet rotating as a solid body. The vectors to the left represent gravity anomalies with respect to a "smooth" gravity field (calculated only from the first few gravitational moments) (see text).

Analogous effects can be seen in Earth's gravity field due to ocean currents

Steady, solid-state mantle convection

Earth's geoid: uncorrelated with topography <u>Not</u> a record of surface processes (instead, mantle convection) <u>Can</u> drive surface processes (e.g., Western Interior Seaway)





flow) causes a *positive* gravity contribution

Earth dynamic topography: amplitude km





Mars' geoid: correlated with topography



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True polar wander – migration of +ve (-ve) nonhydrostatic mass anomalies to equator (poles)

Over geologic time, energy dissipation within viscous interior will align the spin axis with the maximum moment of inertia.



Figure 1

Schematic illustration of the physics of polar wander. The orange circle represents a positive load, the solid blue shell an elastic lithosphere, and the solid gray arrow the rotation vector. In each frame, the dashed blue and orange lines within the interior of the body denote the plane of the rotational bulge and the load, and the solid blue and orange lines denote the maximum principal axis of the rotational bulge and the load, respectively. Panel *a* treats the case in which the rotational bulge can ultimately relax perfectly to any reorientation. In this case, which is the scenario discussed by Gold (1955), an equilibrium theory predicts that the maximum principal axis of the load and the rotation axis will coincide (panel *a*, frame **⑤**). Panel *b* shows the case in which the initial state is hydrostatic but any readjustment of the bulge will introduce elastic stresses in the (initially unstressed) lithosphere. In this case, the rotational bulge cannot adjust perfectly to a reorientation (panel *b*, frame **④**), and the final maximum principal axis of the load and the rotation axis will not coincide (panel *b*, frame **④**). This final state is predicted by the equilibrium theory of Matsuyama et al. (2006) (see Equation 22), and it is governed by a balance between the load-induced forcing and the resistance provided by a remnant rotational bulge (Willemann 1984).

Matsuyama et al., Annual Reviews of Earth & Planetary Science, 2014

Significance of true polar wander

(Potentially rapid) shifts of (paleo)latitude Complicate reconstruction of past climate





Matsuyama & Manga, JGR, 2010

TPW on Earth

less important
 (at least over the past 250 Myr)
 than plate tectonics

- suggests persistence of mantle superplumes



Steinberger & Torsvik, Nature, 2008



Keane et al. Nature 2016

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Next lecture

- How are mountains supported?